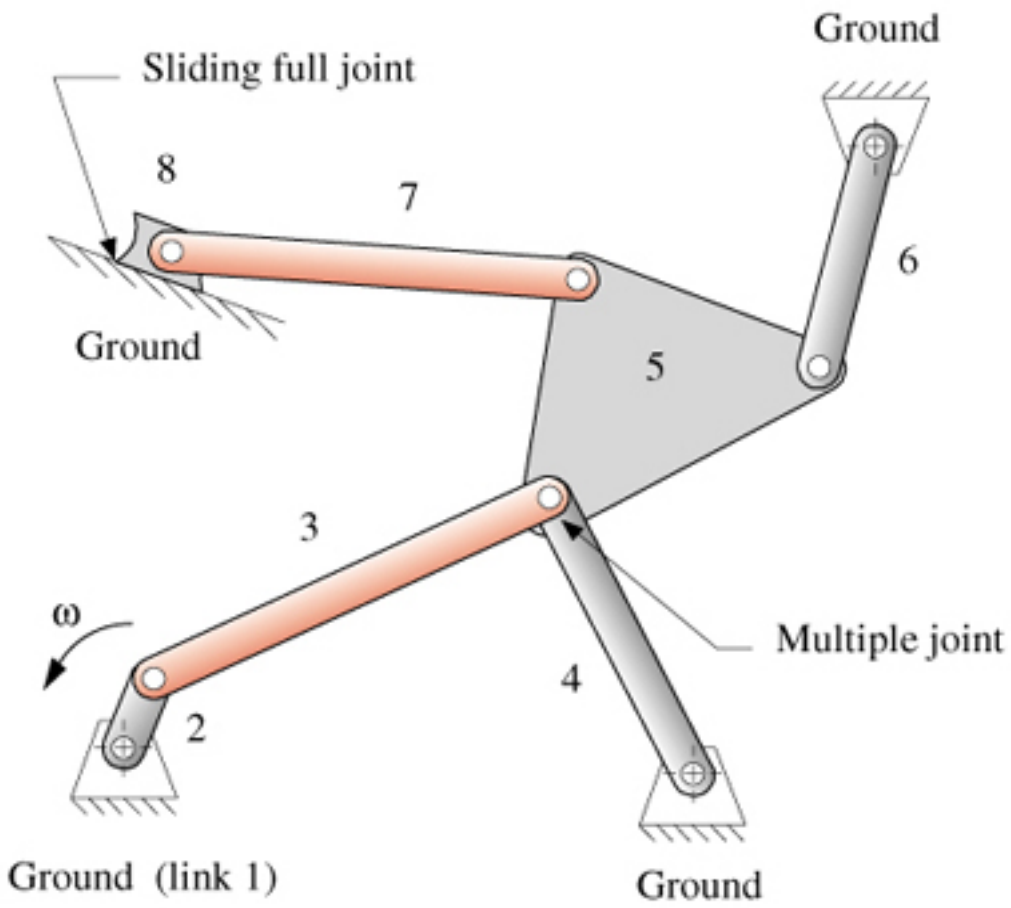
Ödev: Aşağıdaki sistemin kinematik zincirini oluşturun, serb. derc. bulun

Note:
There are no roll-slide (half) joints in this linkage

$L = 8, \quad J = 10$

$DOF = 1$



(a) Linkage with full and multiple joints